

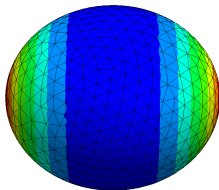
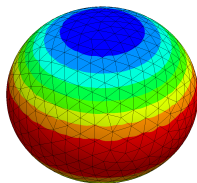
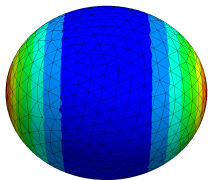
Numerical approximation and optimization of the Canham-Helfrich elastic bending energy

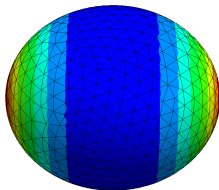
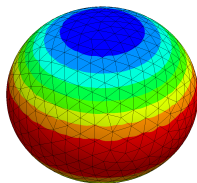
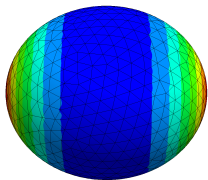
Michael Neunteufel, Joachim Schöberl, Kevin Sturm



AC2T research GmbH

ICOSAHOM 2020/2021, Vienna, July 14, 2021





Curvature

Shape derivative

Solving algorithm

Numerical examples

Canham–Helfrich–Evans energy:

$$\mathcal{W}(\mathcal{S}) = 2\kappa_b \int_{\mathcal{S}} (H - H_0)^2 ds$$

Canham–Helfrich–Evans energy:

κ_b bending elastic constant

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κ_b bending elastic constant

H mean curvature

Canham–Helfrich–Evans energy:

$$\mathcal{W}(S) = 2\kappa_b \int_S (H - H_0)^2 ds$$

κ_b bending elastic constant

H mean curvature

$2H_0$ spontaneous curvature

Canham–Helfrich–Evans energy:

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Constraints:

$$|\Omega| = V_0, \quad |\mathcal{S}| = A_0, \quad V_0 \leq \frac{A_0^{\frac{3}{2}}}{6\sqrt{\pi}}$$

$$\mathcal{J}(\mathcal{S}) = \mathcal{W}(\mathcal{S}) + c_A(|\mathcal{S}| - A_0)^2 + c_V(|\Omega| - V_0)^2$$

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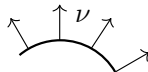
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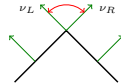
Curvature:

$$H = -\frac{1}{2}\text{tr}(\partial^S \nu)$$

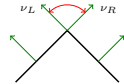


Curvature

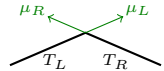
Shape operator $-\partial^S \nu$ is a distribution



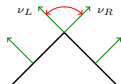
Shape operator $-\partial^S \nu$ is a distribution



- Duality pairing with $\Psi : \mathcal{S} \rightarrow \mathbb{R}_{\text{sym}}^{2 \times 2}$,
 $\mu_L^\top \Psi \mu_L = \mu_R^\top \Psi \mu_R$

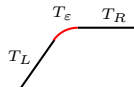
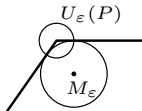
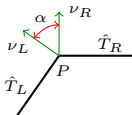
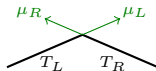


Shape operator $-\partial^S \nu$ is a distribution

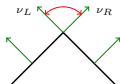


- Duality pairing with $\Psi : \mathcal{S} \rightarrow \mathbb{R}_{\text{sym}}^{2 \times 2}$,

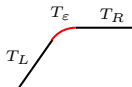
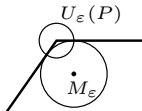
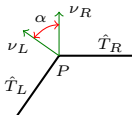
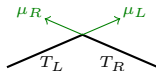
$$\mu_L^\top \Psi \mu_L = \mu_R^\top \Psi \mu_R$$



Shape operator $-\partial^S \nu$ is a distribution

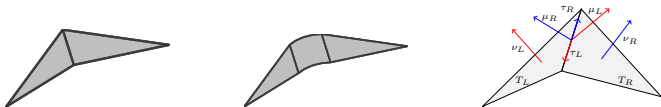


- Duality pairing with $\Psi : \mathcal{S} \rightarrow \mathbb{R}_{\text{sym}}^{2 \times 2}$,
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$$\langle -\partial^S \nu, \Psi \rangle_{\mathcal{T}_h} := - \sum_{T \in \mathcal{T}_h} \int_T \partial^S \nu|_T : \Psi \, ds - \sum_{E \in \mathcal{E}_h} \int_E \angle(\nu_L, \nu_R) \Psi_{\mu\mu} \, d\gamma$$

- [1] GRINSPUN ET. AL., Computing discrete shape operators on general meshes, *Computer Graphics Forum* (2006)



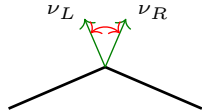
- Direct extension to surfaces
- Ψ is co-normal co-normal continuous HHJ finite element

$$\langle -\partial^S \nu, \Psi \rangle_{\mathcal{T}_h} := - \sum_{T \in \mathcal{T}_h} \int_T \partial^S \nu|_T : \Psi \, ds - \sum_{E \in \mathcal{E}_h} \int_E \llbracket (\nu_L, \nu_R) \Psi_{\mu\mu} \rrbracket d\gamma.$$

- [1] M. COMODI: The Hellan-Herrmann-Johnson method: some new error estimates and postprocessing, *Math. Comp.* (1989)
- [2] A. PECHSTEIN AND J. SCHÖBERL: The TDNNS method for Reissner-Mindlin plates, *J. Numer. Math.* (2017)

Rewrite jump term:

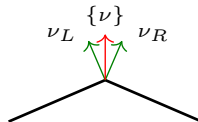
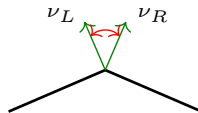
$$\sum_{E \in \mathcal{E}_h} \int_E \llbracket (\nu_L, \nu_R) \Psi_{\mu\mu} \rrbracket d\gamma$$



Rewrite jump term:

$$\sum_{E \in \mathcal{E}_h} \int_E \triangleleft(\nu_L, \nu_R) \Psi_{\mu\mu} d\gamma$$

$$\sum_{T \in \mathcal{T}_h} \int_{\partial T} \triangleleft(\{\nu\}, \nu) \Psi_{\mu\mu} d\gamma$$



$$\{\nu\} := \frac{1}{\|\nu_L + \nu_R\|} (\nu_L + \nu_R)$$

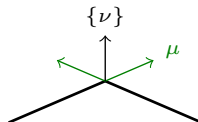
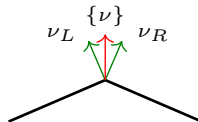
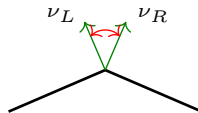
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- Lift distributional curvature to more regular κ

$$\mathcal{L}(\mathcal{T}_h) = \sum_{T \in \mathcal{T}_h} \left(\int_T 2\kappa_b (H - H_0)^2 \right) + c_A J_{\text{surf}}(\mathcal{T}_h) + c_V J_{\text{vol}}(\mathcal{T}_h),$$

- Lift distributional curvature to more regular κ
- σ enforces that $\kappa = -\partial^S \nu$
- κ, σ symmetric, co-normal co-normal continuous

$$\begin{aligned}\mathcal{L}(\mathcal{T}_h, \kappa, \sigma) = & \sum_{T \in \mathcal{T}_h} \left(\int_T 2\kappa_b \left(\frac{1}{2} \text{tr}(\kappa) - H_0 \right)^2 + (\kappa + \partial^S \nu) : \sigma \, ds \right. \\ & + \int_{\partial T} \left(\frac{\pi}{2} - \angle(\mu, \{\nu\}) \right) \sigma_{\mu\mu} \, d\gamma \\ & \left. + c_A J_{\text{surf}}(\mathcal{T}_h) + c_V J_{\text{vol}}(\mathcal{T}_h), \right.\end{aligned}$$

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- Fourth order to second order problems

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- Fourth order to second order problems
- Only $\text{tr}(\kappa)$ involved $\rightarrow$ reduction to scalar-valued κ !

- Additionally $\text{dev}(\boldsymbol{\kappa}) = 0 \Rightarrow \boldsymbol{\kappa} = \kappa \boldsymbol{P}_S, \quad \boldsymbol{P}_S = \boldsymbol{I} - \boldsymbol{\nu} \otimes \boldsymbol{\nu}$

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- $\kappa, \sigma \in H^1(\mathcal{S})$

Shape derivative

$$\mathcal{T}_h^t = \{\mathbf{T}_t(T) : T \in \mathcal{T}_h\}, \quad \mathbf{T}_t(\mathbf{x}) = \mathbf{x} + t \mathbf{X}(\mathbf{x}), \quad \mathbf{x} \in \mathcal{T}_h, t \geq 0 \text{ small}$$

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$$w_t = \det(\partial \mathbf{T}_t) \|\partial \mathbf{T}_t^{-\top} \boldsymbol{\nu}\|, \quad w_t^E = \|\partial \mathbf{T}_t \boldsymbol{\tau}\|,$$

$$\boldsymbol{\nu}^t = \boldsymbol{\nu}_t \circ \mathbf{T}_t = \frac{\partial \mathbf{T}_t^{-\top} \boldsymbol{\nu}}{\|\partial \mathbf{T}_t^{-\top} \boldsymbol{\nu}\|}, \quad \mathbf{A}^\top(t) := \partial \mathbf{T}_t^{-1} (I - \boldsymbol{\nu}^t \otimes \boldsymbol{\nu}^t)$$

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- Shape derivative $D\mathcal{L}(\mathcal{T}_h)(\mathbf{X}) = \lim_{t \searrow 0} \frac{\mathcal{L}(\mathcal{T}_h^t) - \mathcal{L}(\mathcal{T}_h)}{t}$

$$\begin{aligned}\mathcal{L}(\mathcal{T}_h^t, \kappa, \sigma) = & \sum_{T \in \mathcal{T}_h} \left(\int_T \textcolor{brown}{w}_t 2\kappa_b \left(\frac{\kappa}{2} - H_0 \right)^2 + w_t (\kappa + \text{tr}(\partial^S \boldsymbol{\nu}^t \mathbf{A}^\top(t))) \sigma \, ds \right. \\ & + \int_{\partial T} w_t^E \left(\frac{\pi}{2} - \angle(\boldsymbol{\mu}^t, \{\boldsymbol{\nu}^t\}) \right) \sigma \, d\gamma \\ & \left. + c_A J_{\text{surf}}(\mathcal{T}_h^t) + c_V J_{\text{vol}}(\mathcal{T}_h^t) \right).\end{aligned}$$

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$$\frac{d}{dt} w_t|_{t=0} = \text{div}^S(\mathbf{X})$$

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$$DJ_{\text{surf}}(\mathcal{T}_h)(\mathbf{X}) = 2(|\mathcal{T}_h| - A_0) \int_{\mathcal{T}_h} \text{div}^S(\mathbf{X}) \, ds$$

$$\begin{aligned}\mathcal{L}(\mathcal{T}_h^t, \kappa, \sigma) = & \sum_{T \in \mathcal{T}_h} \left(\int_T w_t 2\kappa_b \left(\frac{\kappa}{2} - H_0 \right)^2 + w_t \left(\kappa + \text{tr}(\partial^S \boldsymbol{\nu}^t \mathbf{A}^\top(t)) \right) \sigma \, ds \right. \\ & + \int_{\partial T} w_t^E \left(\frac{\pi}{2} - \angle(\boldsymbol{\mu}^t, \{\boldsymbol{\nu}^t\}) \right) \sigma \, d\gamma \\ & \left. + c_A J_{\text{surf}}(\mathcal{T}_h^t) + c_V J_{\text{vol}}(\mathcal{T}_h^t) \right).\end{aligned}$$

- Shape derivative $D\mathcal{L}(\mathcal{T}_h)(\mathbf{X}) = \lim_{t \searrow 0} \frac{\mathcal{L}(\mathcal{T}_h^t) - \mathcal{L}(\mathcal{T}_h)}{t}$

$$DJ_{\text{vol}}(\mathcal{T}_h)(\mathbf{X}) = 2(|\Omega_h| - V_0) \int_{\mathcal{T}_h} \mathbf{X} \cdot \boldsymbol{\nu} \, ds$$

$$\begin{aligned}\mathcal{L}(\mathcal{T}_h^t, \kappa, \sigma) = & \sum_{T \in \mathcal{T}_h} \left(\int_T w_t 2\kappa_b \left(\frac{\kappa}{2} - H_0 \right)^2 + w_t \left(\kappa + \text{tr}(\partial^S \boldsymbol{\nu}^t \mathbf{A}^\top(t)) \right) \sigma \, ds \right. \\ & + \int_{\partial T} w_t^E \left(\frac{\pi}{2} - \angle(\boldsymbol{\mu}^t, \{\boldsymbol{\nu}^t\}) \right) \sigma \, d\gamma \\ & \left. + c_A J_{\text{surf}}(\mathcal{T}_h^t) + c_V J_{\text{vol}}(\mathcal{T}_h^t) \right).\end{aligned}$$

- Shape derivative $D\mathcal{L}(\mathcal{T}_h)(\mathbf{X}) = \lim_{t \searrow 0} \frac{\mathcal{L}(\mathcal{T}_h^t) - \mathcal{L}(\mathcal{T}_h)}{t}$

Shape operator

$$\begin{aligned} \frac{d}{dt}(\partial^{S_t} \nu_t) \circ \mathbf{T}_t|_{t=0} &= \partial^S \nu \left(2 \operatorname{Sym}(\nu \otimes \nu \partial^S \mathbf{X}) - \partial^S \mathbf{X} \right) \\ &\quad - \operatorname{hess}(\mathbf{X})(\nu) - \partial^S \mathbf{X}^\top \partial^S \nu \end{aligned}$$

Mean curvature

$$\frac{d}{dt} \operatorname{tr}(\partial^{S_t} \nu_t) \circ \mathbf{T}_t|_{t=0} = -\Delta^S \mathbf{X} \cdot \nu - 2 \partial^S \mathbf{X} : \partial^S \nu$$

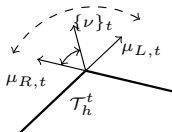
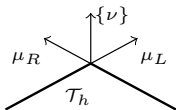
Laplace–Beltrami operator $\Delta^S = \operatorname{div}^S(\partial^S)$

Shape operator

$$\begin{aligned} \frac{d}{dt}(\partial^{S_t} \nu_t) \circ \mathbf{T}_t|_{t=0} &= \partial^S \nu \left(2 \operatorname{Sym}(\nu \otimes \nu \partial^S \mathbf{X}) - \partial^S \mathbf{X} \right) \\ &\quad - \operatorname{hess}(\mathbf{X})(\nu) - \partial^S \mathbf{X}^\top \partial^S \nu \end{aligned}$$

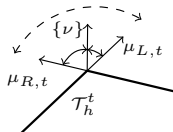
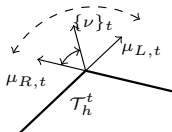
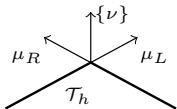
Mean curvature (weak form)

$$\begin{aligned} \int_T \operatorname{tr}(\partial^{S_t} \nu_t) \circ \mathbf{T}_t|_{t=0} \sigma \, ds &= \int_T \partial^S \mathbf{X} \partial^S \sigma \cdot \nu - \partial^S \mathbf{X} : \partial^S \nu \sigma \, ds \\ &\quad - \int_{\partial T} \partial^S \mathbf{X} \mu \cdot \nu \sigma \, d\gamma \end{aligned}$$



$$\int_{\partial T} \left(\frac{\pi}{2} - \angle(\boldsymbol{\mu}^t, \{\boldsymbol{\nu}\}^t) \right) \sigma \, d\gamma$$

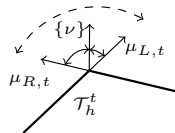
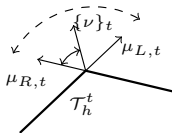
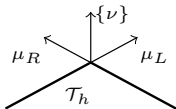
$$\{\boldsymbol{\nu}\}^t = \frac{1}{\|\boldsymbol{\nu}_L^t + \boldsymbol{\nu}_R^t\|} (\boldsymbol{\nu}_L^t + \boldsymbol{\nu}_R^t)$$



$$\int_{\partial T} \left(\frac{\pi}{2} - \angle(\boldsymbol{\mu}^t, \{\boldsymbol{\nu}\}^t) \right) \sigma d\gamma$$

$$\{\boldsymbol{\nu}\}^t = \frac{1}{\|\boldsymbol{\nu}_L^t + \boldsymbol{\nu}_R^t\|} (\boldsymbol{\nu}_L^t + \boldsymbol{\nu}_R^t)$$

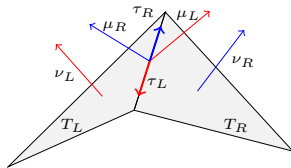
$$\int_{\partial T} \left(\frac{\pi}{2} - \angle(\boldsymbol{\mu}^t, \{\boldsymbol{\nu}\}) \right) \sigma d\gamma$$



$$\int_{\partial T} \left(\frac{\pi}{2} - \angle(\mu^t, \{\nu\}^t) \right) \sigma d\gamma$$

$$\mathbf{P}_{\tau^t}^\perp(\{\nu\}) := \frac{\{\nu\} - (\{\nu\} \cdot \tau^t) \tau^t}{\| \{\nu\} - (\{\nu\} \cdot \tau^t) \tau^t \|}$$

$$\int_{\partial T} \left(\frac{\pi}{2} - \angle(\mu^t, \mathbf{P}_{\tau^t}^\perp(\{\nu\})) \right) \sigma d\gamma$$



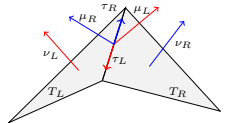
Shape derivative jump term

$$\frac{d}{dt} \angle(\boldsymbol{\mu}^t, \mathbf{P}_{\boldsymbol{\tau}^t}^\perp(\{\boldsymbol{\nu}\}))|_{t=0} = - \frac{(\partial^S \mathbf{X} - \partial^S \mathbf{X}^\top) \boldsymbol{\mu} \cdot \{\boldsymbol{\nu}\}}{\sqrt{1 - (\boldsymbol{\mu} \cdot \{\boldsymbol{\nu}\})^2}}$$

Shape derivative jump term

$$\frac{d}{dt} \langle (\boldsymbol{\mu}^t, \mathbf{P}_{\boldsymbol{\tau}^t}^\perp(\{\boldsymbol{\nu}\})) \rangle|_{t=0} = - \frac{(\partial^S \mathbf{X} - \partial^S \mathbf{X}^\top) \boldsymbol{\mu} \cdot \{\boldsymbol{\nu}\}}{\sqrt{1 - (\boldsymbol{\mu} \cdot \{\boldsymbol{\nu}\})^2}}$$

- Same **first** shape derivative as for $\langle (\boldsymbol{\mu}^t, \{\boldsymbol{\nu}\}) \rangle$
- $\frac{d}{dt} \boldsymbol{\mu}^t|_{t=0} = ((\mathbf{I} - \boldsymbol{\tau} \otimes \boldsymbol{\tau}) \partial^S \mathbf{X} - \partial^S \mathbf{X}^\top) \boldsymbol{\mu}$



- For fixed $\mathcal{T}_h$, κ , and σ

$$\begin{aligned}
 D\mathcal{L}(\mathcal{T}_h)(\mathbf{X}) = & \sum_{T \in \mathcal{T}_h} \left(\int_T \operatorname{div}^S(\mathbf{X}) \left(2\kappa_b \left(\frac{\kappa}{2} - H_0 \right)^2 + (\kappa + \operatorname{tr}(\partial^S \boldsymbol{\nu})) \sigma \right) \right. \\
 & + \partial^S \mathbf{X} \partial^S \sigma \cdot \boldsymbol{\nu} - \partial^S \mathbf{X} : \partial^S \boldsymbol{\nu} \sigma \, ds - \int_{\partial T} \partial^S \mathbf{X} \boldsymbol{\mu} \cdot \boldsymbol{\nu} \sigma \, d\gamma \\
 & + \int_{\partial T} \left(\partial^S \mathbf{X}_{\tau\tau} \left(\frac{\pi}{2} - \angle(\boldsymbol{\mu}, \{\boldsymbol{\nu}\}) \right) + \frac{(\partial^S \mathbf{X} - \partial^S \mathbf{X}^\top) \boldsymbol{\mu} \cdot \{\boldsymbol{\nu}\}}{\sqrt{1 - (\boldsymbol{\mu} \cdot \{\boldsymbol{\nu}\})^2}} \right) \sigma \, d\gamma \Big) \\
 & + c_A D J_{\text{surf}}(\mathcal{T}_h)(\mathbf{X}) + c_V D J_{\text{vol}}(\mathcal{T}_h)(\mathbf{X})
 \end{aligned}$$

- For fixed $\mathcal{T}_h$, κ , and σ
- lowest-order: lifting only via jump term

$$\begin{aligned}
 D\mathcal{L}(\mathcal{T}_h)(\mathbf{X}) = & \sum_{T \in \mathcal{T}_h} \left(\int_T \operatorname{div}^S(\mathbf{X}) \left(2\kappa_b \left(\frac{\kappa}{2} - H_0 \right)^2 + (\kappa \right) \sigma \right) \right. \\
 & + \int_{\partial T} \left(\partial^S \mathbf{X}_{\tau\tau} \left(\frac{\pi}{2} - \angle(\boldsymbol{\mu}, \{\boldsymbol{\nu}\}) \right) + \frac{(\partial^S \mathbf{X} - \partial^S \mathbf{X}^\top) \boldsymbol{\mu} \cdot \{\boldsymbol{\nu}\}}{\sqrt{1 - (\boldsymbol{\mu} \cdot \{\boldsymbol{\nu}\})^2}} \right) \sigma \, d\gamma \\
 & \left. + c_A DJ_{\text{surf}}(\mathcal{T}_h)(\mathbf{X}) + c_V DJ_{\text{vol}}(\mathcal{T}_h)(\mathbf{X}) \right)
 \end{aligned}$$

- For fixed $\mathcal{T}_h$, κ , and σ
- lowest-order: lifting only via jump term

$$\begin{aligned}
 D\mathcal{L}(\mathcal{T}_h)(\mathbf{X}) = & \sum_{T \in \mathcal{T}_h} \left(\int_T \operatorname{div}^S(\mathbf{X}) \left(2\kappa_b \left(\frac{\kappa}{2} - H_0 \right)^2 + (\kappa \right) \sigma \right) \right. \\
 & + \int_{\partial T} \left(\partial^S \mathbf{X}_{\tau\tau} \left(\frac{\pi}{2} - \angle(\boldsymbol{\mu}, \{\boldsymbol{\nu}\}) \right) + \frac{(\partial^S \mathbf{X} - \partial^S \mathbf{X}^\top) \boldsymbol{\mu} \cdot \{\boldsymbol{\nu}\}}{\sqrt{1 - (\boldsymbol{\mu} \cdot \{\boldsymbol{\nu}\})^2}} \right) \sigma \, d\gamma \\
 & \left. + c_A DJ_{\text{surf}}(\mathcal{T}_h)(\mathbf{X}) + c_V DJ_{\text{vol}}(\mathcal{T}_h)(\mathbf{X}) \right)
 \end{aligned}$$

Solving algorithm

For fixed $\mathcal{T}_h$

find κ , such that $\partial_\sigma \mathcal{L}(\mathcal{T}_h, \kappa, \sigma)(\delta\sigma) = 0$ for all $\delta\sigma \in V_h(\mathcal{T}_h)$,

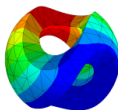
find σ , such that $\partial_\kappa \mathcal{L}(\mathcal{T}_h, \kappa, \sigma)(\delta\kappa) = 0$ for all $\delta\kappa \in V_h(\mathcal{T}_h)$,

$$\begin{aligned}\partial_\sigma \mathcal{L}(\mathcal{T}_h, \kappa, \sigma)(\delta\sigma) &= \sum_{T \in \mathcal{T}_h} \left(\int_T \kappa \delta\sigma + \text{tr}(\partial^S \boldsymbol{\nu}) \delta\sigma \, ds \right. \\ &\quad \left. + \int_{\partial T} \left(\frac{\pi}{2} - \angle(\boldsymbol{\mu}, \mathbf{P}_\tau^\perp(\{\boldsymbol{\nu}\})) \right) \delta\sigma \, d\gamma \right) \\ \partial_\kappa \mathcal{L}(\mathcal{T}_h, \kappa, \sigma)(\delta\kappa) &= \int_{\mathcal{T}_h} 2\kappa_b \left(\frac{\kappa}{2} - H_0 \right) \delta\kappa + \delta\kappa \sigma \, ds\end{aligned}$$

- 1: **Input:** surface $\mathcal{T}_h^0$, $n = 0$, $N_{\max} > 0$, $\epsilon > 0$, $\alpha > 0$
- 2: **Output:** optimal shape $\mathcal{T}_h^*$
- 3: **while** $n \leq N_{\max}$ and $|\nabla \mathcal{J}(\mathcal{T}_h^n)| > \epsilon$ **do**
- 4: **if** $\mathcal{J}((\text{id} - \alpha \nabla \mathcal{J}(\mathcal{T}_h^n))(\mathcal{T}_h^n)) \leq \mathcal{J}(\mathcal{T}_h^n)$ **then**
- 5: $\mathcal{T}_h^{n+1} \leftarrow (\text{id} - \alpha \nabla \mathcal{J}(\mathcal{T}_h^n))(\mathcal{T}_h^n)$
- 6: $n \leftarrow n + 1$, increase α
- 7: **else**
- 8: reduce α
- 9: **end if**
- 10: **end while**

One iteration on $\mathcal{T}_h^n$ involves

1. Average normal vector and solve (adjoint) state problem
2. With new κ and σ compute shape gradient



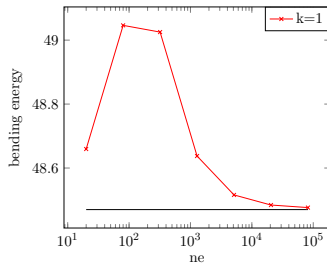
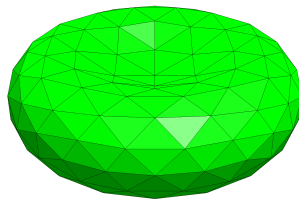
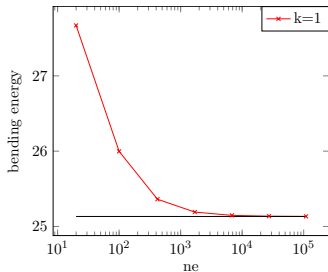
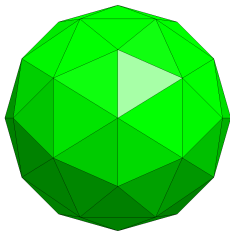
NGSolve ¹

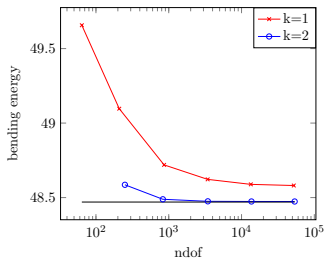
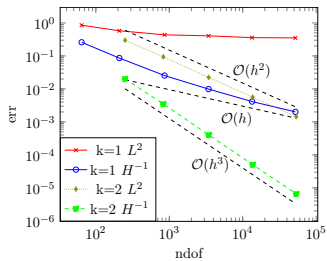
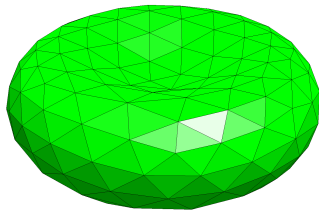
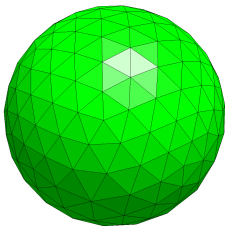
- Fully automated shape differentiation
- Deform mesh via ALE without remeshing

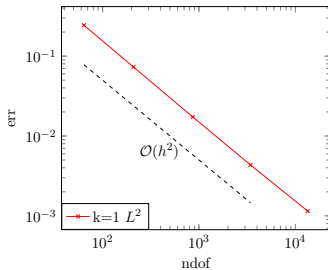
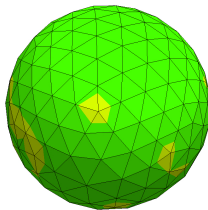
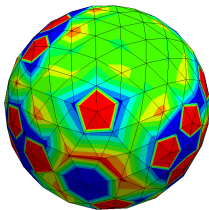
[1] GANGL, STURM, N., SCHÖBERL, Fully and Semi-Automated Shape Differentiation in NGSolve, *Structural and Multidisciplinary Optimization* (2021)

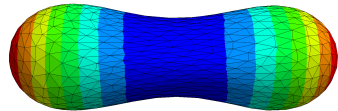
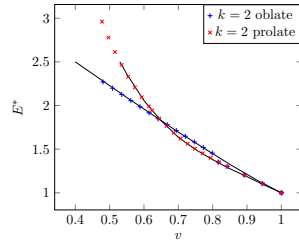
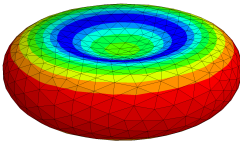
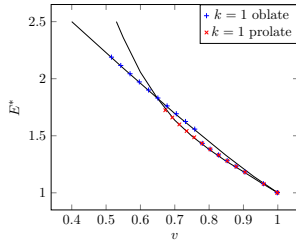
¹www.ngsolve.org

Numerical examples



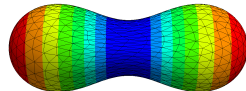
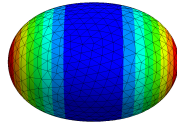
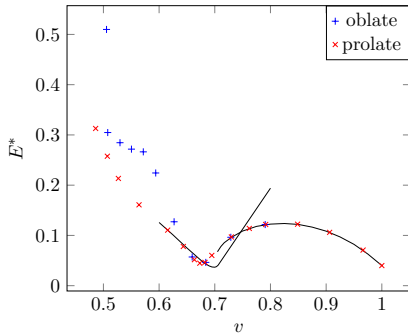




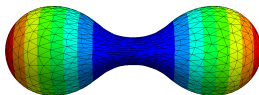
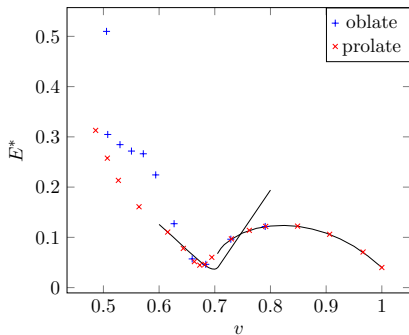


- [1] SEIFERT, BERNDL, LIPOWSKY, Shape transformations of vesicles: Phase diagram for spontaneous- curvature and bilayer-coupling models, *Phys. Rev. A* (1991)

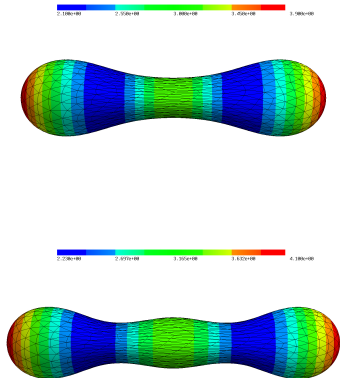
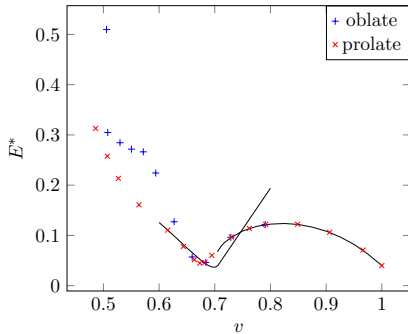
- $\mathcal{W}(\mathcal{S}) = 2\kappa_b \int_{\mathcal{S}} (H - H_0)^2 ds, H_0 = 1.2$



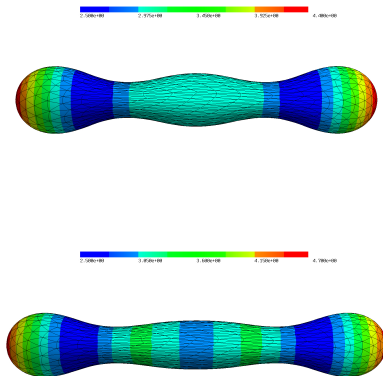
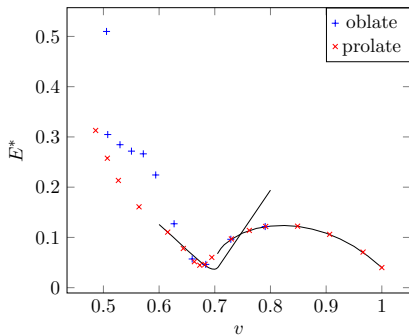
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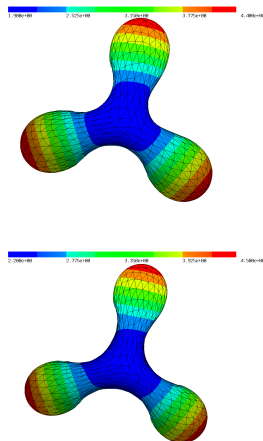
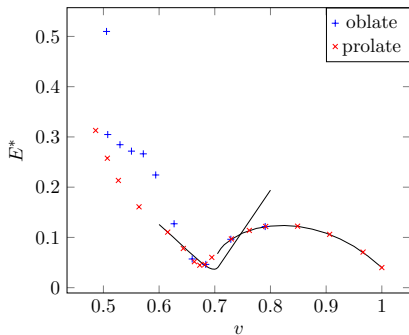
- $\mathcal{W}(\mathcal{S}) = 2\kappa_b \int_{\mathcal{S}} (H - H_0)^2 ds, H_0 = 1.2$



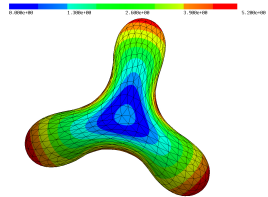
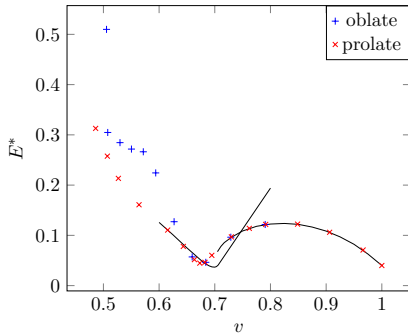
- $\mathcal{W}(\mathcal{S}) = 2\kappa_b \int_{\mathcal{S}} (H - H_0)^2 ds, H_0 = 1.2$



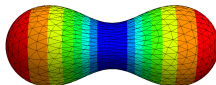
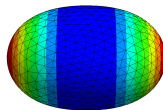
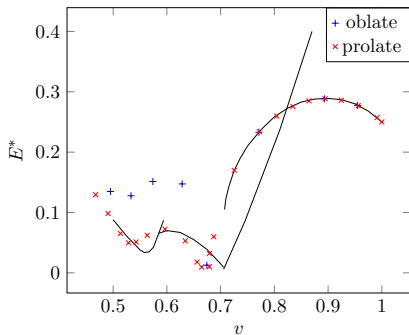
- $\mathcal{W}(\mathcal{S}) = 2\kappa_b \int_{\mathcal{S}} (H - H_0)^2 ds$, $H_0 = 1.2$



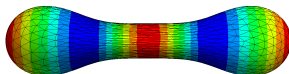
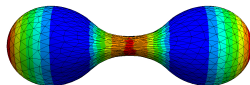
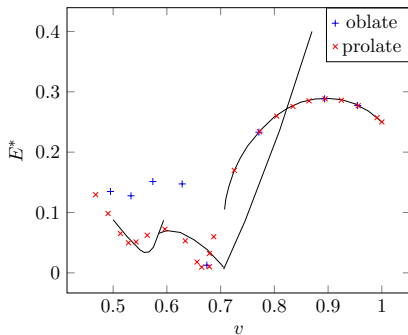
- $\mathcal{W}(\mathcal{S}) = 2\kappa_b \int_{\mathcal{S}} (H - H_0)^2 ds, H_0 = 1.2$



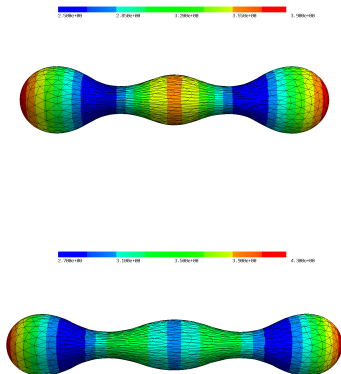
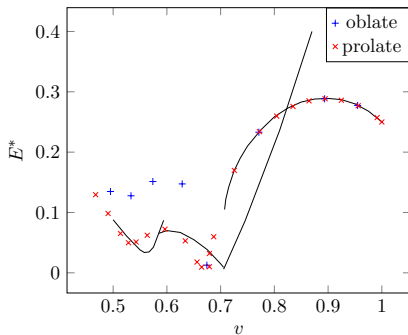
- $\mathcal{W}(\mathcal{S}) = 2\kappa_b \int_{\mathcal{S}} (H - H_0)^2 ds$, $H_0 = 1.5$



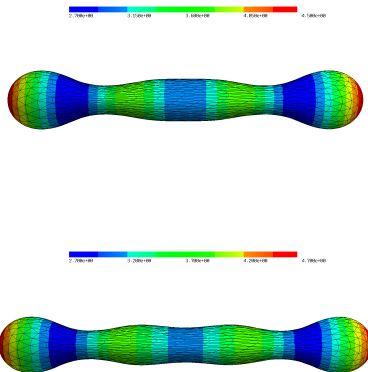
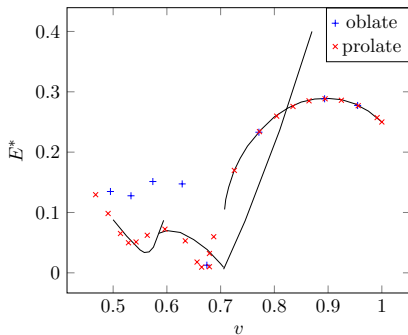
- $\mathcal{W}(\mathcal{S}) = 2\kappa_b \int_{\mathcal{S}} (H - H_0)^2 ds, H_0 = 1.5$



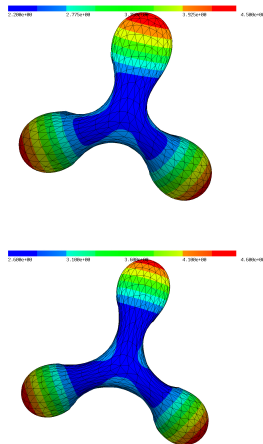
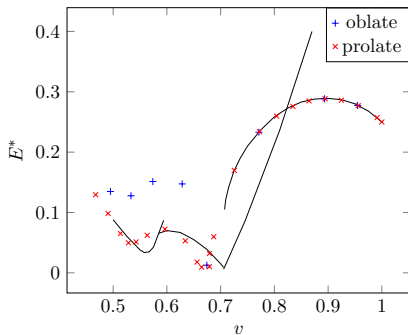
- $\mathcal{W}(\mathcal{S}) = 2\kappa_b \int_{\mathcal{S}} (H - H_0)^2 ds, H_0 = 1.5$



- $\mathcal{W}(\mathcal{S}) = 2\kappa_b \int_{\mathcal{S}} (H - H_0)^2 ds, H_0 = 1.5$



- $\mathcal{W}(\mathcal{S}) = 2\kappa_b \int_{\mathcal{S}} (H - H_0)^2 ds$, $H_0 = 1.5$



- Lifting distributional curvature by three-field formulation
- General shape derivative

- Lifting distributional curvature by three-field formulation
- General shape derivative
- Remeshing

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- General shape derivative
- Remeshing

- [1] N., SCHÖBERL, STURM, Numerical shape optimization of Canham-Helfrich-Evans bending energy, *in preparation*
- [2] GANGL, STURM, N., SCHÖBERL, Fully and Semi-Automated Shape Differentiation in NGSolve, *Structural and Multidisciplinary Optimization (2021)*

- Lifting distributional curvature by three-field formulation
- General shape derivative
- Remeshing

Thank You for Your attention!

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